## Vision™ OPLC™

V130-33-RA22/V130-J-RA22 V350-35-RA22/V350-J-RA22 V430-J-RA22

V130-33-TRA22/V130-J-TRA22 V350-35-TRA22/V350-J-TRA22 V430-J-TRA22

# **Installation Guide**

- 12 Digital Inputs, including 1 HSC/Shaft-encoder Inputs, 2 Analog, 2 PT100/TC inputs
- 8 Relay Outputs 2 Analog Outputs
- 12 Digital Inputs, including 1 HSC/Shaft-encoder Inputs, 2 Analog Inputs, 2 PT100/TC inputs
- 4 Relay Outputs
  2 Analog Outputs
- 4 high-speed npn Transistor Outputs

## **General Description**

All of the controllers covered in this guide are micro-OPLCs, rugged programmable logic controllers that comprise built-in operating panels and on-board I/Os.

V130-RA22 V130J-RA22		V130-TRA22 V130J-TRA22	V350-RA22 V350J-RA22	V350-TRA22 V350J-TRA22	V430J-RA22 V430J-TRA22		
On-board I/O			Model Dependent				
Screen	2	2.4"	3.5" Co	3.5" Color Touch 4.3" Color Tou			
Keypad	,	⁄es		None			
Function Keys	N	one	Yes				
Com Port, Built-in							
RS232/485	Yes	Yes	Yes	Yes	Yes*		
USB device, mini-B			None	None	Yes*		
Com Ports, separate order, user-installed	The user may install a CANbus port (V100-17-CAN), and <u>one</u> of the following:  RS232/RS485 port (V100-17-RS4/V100-17-RS4X)  Ethernet (V100-17-ET2)  Profibus Slave (V100-17-PB1)						

**Standard Kit Contents** 

Item	V130-RA22 V130J-RA22	V130-TRA22 V130J-TRA22	V350-RA22 V350J-RA22	V350-TRA22 V350J-TRA22	V430J-RA22 V430J-TRA22	
Controller		Yes				
Terminal Blocks		Yes				
Battery (installed)		Yes				
Slides (2 sets of key labels)	None Ye			Yes	None	
Mounting Brackets		Yes (2 parts)			Yes (4 parts)	
Rubber Seal		Yes				
Programming cable + RS232 adapter	Yes			None		
USB programming cable	None			Yes		

## **Alert Symbols and General Restrictions**

When any of the following symbols appear, read the associated information carefully.

Symbol	Meaning	Description
1	Danger	The identified danger causes physical and property damage.
<u>^</u> !\	Warning	The identified danger could cause physical and property damage.
Caution	Caution	Use caution.

- Before using this product, the user must read and understand this document.
- All examples and diagrams are intended to aid understanding, and do not guarantee operation.
   Unitronics accepts no responsibility for actual use of this product based on these examples.
- Please dispose of this product according to local and national standards and regulations.
- Only qualified service personnel should open this device or carry out repairs.



- Failure to comply with appropriate safety guidelines can cause severe injury or property damage.
- <u>^!\</u>
- Do not attempt to use this device with parameters that exceed permissible levels.
- To avoid damaging the system, do not connect/disconnect the device when power is on.

## **Environmental Considerations**

- Do not install in areas with: excessive or conductive dust, corrosive or flammable gas, moisture or rain, excessive heat, regular impact shocks or excessive vibration, in accordance with the standards given in the product's technical specification sheet.
- Do not place in water or let water leak onto the unit.
- Do not allow debris to fall inside the unit during installation.
- <u>^</u>!\

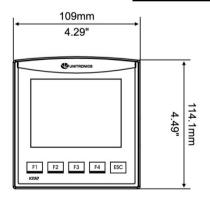
13

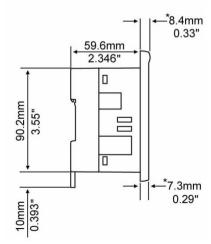
- Ventilation: 10mm space required between controller's top/bottom edges & enclosure walls.
- Install at maximum distance from high-voltage cables and power equipment.

## Mounting

Note that figures are for illustrative purposes only.

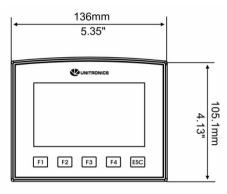
#### Dimensions: V130/V350/V130J/V350J

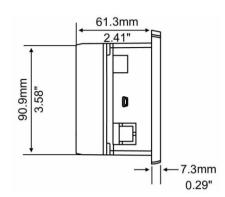




Note that for models V130J/V350J, the bezel width is 6.7 mm (0.26").

## **Dimensions: V430J**





#### **Panel Mounting**

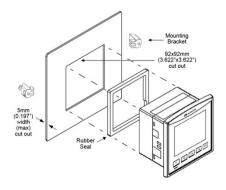
Before you begin, note that the mounting panel cannot be more than 5 mm thick.

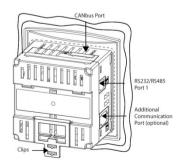
#### UL listed models:

To meet the UL508 standard, panel-mount the device on the flat surface of a Type 1 enclosure.

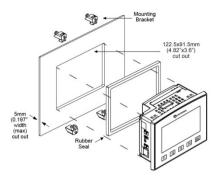
- 1. Make a panel cut-out of the appropriate size:
- V130/V350/V130J/V350J: 92x92 mm (3.622"x3.622").
- V430J: 122.5x91.5 mm (4.82"x3.6").
- 2. Slide the controller into the cut-out, ensuring that the rubber seal is in place.
- 3. Push the mounting brackets into their slots on the sides of the panel as shown in the figure below.
- Tighten the bracket's screws against the panel. Hold the bracket securely against the unit while tightening the screw.
- When properly mounted, the controller is squarely situated in the panel cut-out as shown in the accompanying figures.

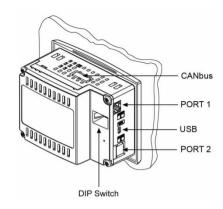
### V130/V350/V130J/V350J





## V430J

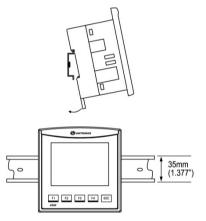




# DIN-rail Mounting (V130/V350/V130J/V350J)

1. Snap the controller onto the DIN rail as shown in the figure to the right.

2. When properly mounted, the controller is squarely situated on the DIN-rail as shown in the figure to the right.



## Wiring



- Do not touch live wires.
- Install an external circuit breaker. Guard against short-circuiting in external wiring.



- Use appropriate circuit protection devices.
- Unused pins should not be connected. Ignoring this directive may damage the device.
- Double-check all wiring before turning on the power supply.
- To avoid damaging the wire, do not exceed a maximum torque of 0.5 N·m (5 kgf·cm).

#### Caution

- Do not use tin, solder, or any substance on stripped wire that might cause the wire strand to break.
- Install at maximum distance from high-voltage cables and power equipment.

#### Wiring Procedure

Use crimp terminals for wiring; use 3.31 mm <sup>2</sup> –0.13 mm<sup>2</sup> wire (12-16 AWG):

- 1. Strip the wire to a length of 7±0.5mm (0.270–0.300").
- 2. Unscrew the terminal to its widest position before inserting a wire.
- 3. Insert the wire completely into the terminal to ensure a proper connection.
- 4. Tighten enough to keep the wire from pulling free.
- Input or output cables should not be run through the same multi-core cable or share the same wire.
- Allow for voltage drop and noise interference with I/O lines used over an extended distance.
   Use wire that is properly sized for the load.
- The controller and I/O signals must be connected to the same 0V signal.

#### I/Os

V130/V350/V130J/V350J/V430J-RA22 models comprise a total of 12 inputs, 8 relay outputs and 2 analog outputs.

V130/V350/V130J/V350J/V430J-TRA22 models comprise a total of 12 inputs, 4 relays outputs, 4 npn outputs and 2 analog outputs.

Input functionality can be adapted as follows:

12 inputs may be used as digital inputs. They may be wired, in a group, and set to either npn or pnp via a single jumper.

In addition, according to jumper settings and appropriate wiring:

- Inputs 5 and 6 can function as either digital or analog inputs.
- Input 0 can function as high-speed counter, as part of a shaft-encoder, or as normal digital input.
- Input 1 can function as either counter reset, as part of a shaft-encoder, or as normal digital input.
- If input 0 is set as high-speed counters (without reset), input 1 can function as normal digital input.
- Inputs 7-8 and 9-10 can function as digital, thermocouple, or PT100 inputs; Input 11 can also serve as the CM signal for PT100.

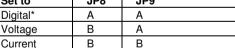
## **Input Jumper Settings**

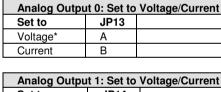
The tables below show how to set a specific jumper to change input functionality. To access the I/O jumpers, you must open the controller according to the instructions beginning on page 13.



Incompatible jumper settings and wiring connections may seriously damage the controller.

Digital Inputs 0-11: Set Type							
Set to	JP12 (all Inputs)						
npn (sink)	A						
pnp (source)*	В	В					
Inputs 7/8: Set	Type - Di	gital or R	ΓD/TC #1				
Set to	JP1	JP2	JP3				
Digital*	Α	Α	Α				
Thermocouple	В	В	В				
PT100	В	Α	В				
Inputs 9/10: Se	t Type - D	igital or F	RTD/TC #0				
Set to	JP5	JP6	JP7				
Digital*	Α	Α	Α				
Thermocouple	В	В	В				
PT100	В	Α	В				
Input 11: Set Type - Digital or CM for PT100							
Set to	JP11						
Digital*	Α						
CM for PT100	В						
Input 5: Set Ty	pe - Digita	al or Anal	og #3				
Set to	JP4	JP10					
Digital*	Α	Α					
Voltage	В	Α					
Current	В	В					
Input 6: Set Ty	pe - Digita	al or Analo	og #2				
Set to	JP8	JP9	· · · · · · · · · · · · · · · · · · ·				
Digital*	Α	Α	·				
Voltage	В	Α					
Current	В	В					





14 13 A	
	_

Analog Output 1: Set to Voltage/Current				
Set to	JP14			
Voltage*	Α			
Current	В			

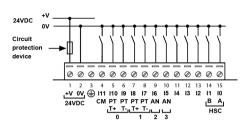
<sup>\*</sup>Default settings

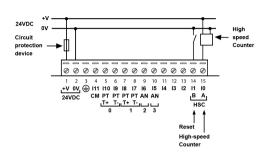
## I/O Wiring

#### npn (sink) Input

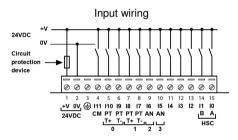


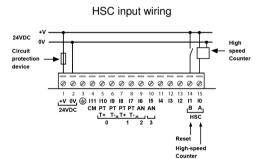
HSC input wiring



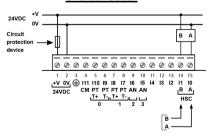


#### pnp (source) Input





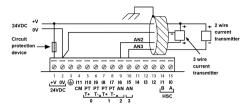
#### Shaft-encoder

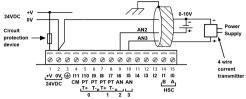


### **Analog Input**

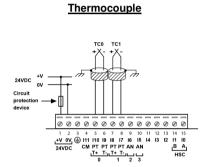
Analog input wiring, current (2/3 wire)

Analog input wiring, current (4-wire), and voltage





- Shields should be connected at the signal's source.
- The 0V signal of the analog input must be connected to the controller's 0V.

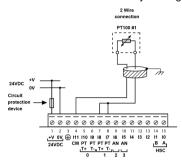


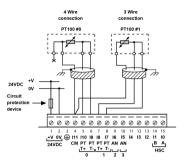
- Thermocouple 0: use Input 9 as negative input and 10 as positive.
- Thermocouple 1: use Input 7 as negative input and 8 as positive.

Туре	Temp. Range	Wire Color		
		ANSI (USA)	BS1843 (UK)	
mV	-5 to 56mV			
В	200 to 1820°C	+Grey	+None	
Ь	(300 to 3276°F)	-Red	-Blue	
F	-200 to 750°C	+Violet	+Brown	
_	(-328 to 1382°F)	-Red	-Blue	
J	-200 to 760°C	+White	+Yellow	
J	(-328 to 1400°F)	-Red	-Blue	
K	-200 to 1250°C	+Yellow	+Brown	
	(-328 to 2282°F)	-Red	-Blue	
N	-200 to 1300°C	+Orange	+Orange	
IN	(-328 to 2372°F)	-Red	-Blue	
R	0 to 1768°C	+Black	+White	
n	(32 to 3214°F)	-Red	-Blue	
S	0 to 1768°C	+Black	+White	
	(32 to 3214°F)	-Red	-Blue	
Т	-200 to 400°C	+Blue	+White	
ı	(-328 to 752°F)	-Red	-Blue	

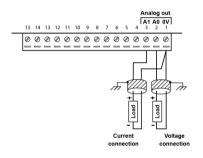
#### RTD

- PT100 (Sensor 0): use Input 9 and 10, related to CM signal.
- PT100 (Sensor 1): use Input 7 and 8, related to CM signal.
- 4 wire PT100 can be used by leaving one of the sensor leads unconnected.

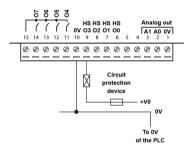




#### **Analog Outputs**

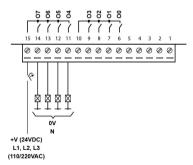


## npn Outputs (TRA22)

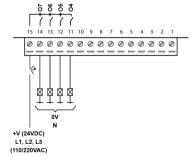


#### **Relay Outputs**

#### **RA22**



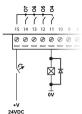
# TRA22

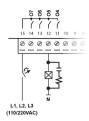


#### **Increasing Contact Life Span**

To increase the life span of the relay output contacts and protect the device from potential damage by reverse EMF, connect:

- A clamping diode in parallel with each inductive DC load
- An RC snubber circuit in parallel with each inductive AC load





## **Power Supply**

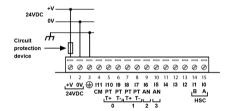
The controller requires an external 24VDC power supply.



- The power supply must include double insulation. Outputs must be rated as SELV/PELV/Class2/Limited Power.
- Use separate wires to connect the functional earth line (pin 3) and the 0V line (pin 2) to the system earth ground.
- Install an external circuit breaker. Guard against short-circuiting in external wiring.



- Double-check all wiring before turning on the power supply.
- Do not connect either the 'Neutral' or 'Line' signal of the 110/220VAC to device's 0V pin
- In the event of voltage fluctuations or nonconformity to voltage power supply specifications, connect the device to a regulated power supply.



## **Earthing the OPLC**

To maximize system performance, avoid electromagnetic interference by:

- Mounting the controller on a metal panel.
- Connect each common and ground connection directly to the earth ground of your system.
- For ground wiring uses the shortest and thickest possible wire.

#### Communication

V130/V350/V130J/V350J

These models comprise a built-in RS232/RS485 serial port (Port 1)

V430J

These models comprise built-in ports: 1 USB and 1 RS232/RS485 (Port 1).

Note that physically connecting a PC to the controller via USB suspends RS232/RS485 communications via Port 1. When the PC is disconnected, RS232/RS485 resumes.

#### RS232/RS485 Port



- Turn off power before making communications connections.
- Caution
- Always use the appropriate port adapters.
- Signals are related to the controller's 0V; the same 0V is used by the power supply.

Caution

- The serial port is not isolated. If the controller is used with a non-isolated external device, avoid potential voltage that exceeds ± 10V.
- Use RS232 to download programs from a PC, and to communicate with serial devices and applications, such as SCADA.
- Use RS485 to create a multi-drop network containing up to 32 devices.

#### **Pinouts**

The pinouts below show the PLC port signals.

RS232	
Pin#	Description
1*	DTR signal
2	0V reference
3	TXD signal
4	RXD signal
5	0V reference
6*	DSR signal

RS485**		Controller Port
Pin#	Description	
1	A signal (+)	
2	(RS232 signal)	[
3	(RS232 signal)	
4	(RS232 signal)	Pin #1
5	(RS232 signal)	
6	B signal (-)	

<sup>\*</sup> Standard programming cables do not provide connection points for pins 1 and 6.

Note that it is possible to establish a PC to PLC connection using RS232 even when the PLC is set to RS485 (this eliminates the need to open the controller to set jumpers).

To do so, remove the RS485 connector (pins 1 & 6) from the PLC and connect a standard RS232 programming cable.

Note that this is possible only if DTR and DSR signals of RS232 are not used (which is the standard case).

<sup>\*\*</sup> When a port is adapted to RS485, Pin 1 (DTR) is used for signal A, and Pin 6 (DSR) signal is used for signal B.

#### Setting RS232/RS485 Communication Parameters, V130/V350/V130J/V350J

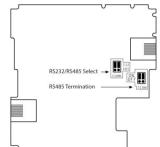
This port may be set to either RS232 or RS485 via jumper.

The accompanying figure shows the jumper factory default settings.

These jumpers may be used to:

- Set communications to RS485, by setting both COMM jumpers to '485'.
- Set RS485 termination, by setting both TERM jumpers to 'OFF'.

To access the jumpers, you must open the controller according to the instructions on page 13.



## Setting RS232/RS485 Communication Parameters, V430J

This port may be set to either RS232 or RS485 via DIP switches:

The table shows the DIP switches factory default settings. Use the table to adapt the settings.

	Switch Settings					
	1 2 3 4 5 6					
RS232*	ON	OFF	OFF	ON	OFF	OFF
RS485	OFF	ON	ON	OFF	OFF	OFF
RS485 with termination**	OFF	ON	ON	OFF	ON	ON

<sup>\*</sup> Default factory setting

## **USB Port**

Caution

The USB port is not isolated.
 Make sure that the PC and the controller are grounded to same potential.

The USB port may be used for programming, OS download, and PC access.

<sup>\*\*</sup> Causes the unit to function as an end unit in an RS485 network

### **Opening the Controller**



- Before performing these actions, touch a grounded object to discharge any electrostatic charge.
- Avoid touching the PCB board directly. Hold the PCB board by its connectors.
- 1. Turn off the power supply, disconnect, and dismount the controller.
- 2. The back cover of the controller comprises 4 screws, located in the corners. Remove the screws, and pull off the back cover.

### Changing I/O Settings

After opening the controller and exposing the I/O board, you can change the jumper settings according to the table shown above.

#### Changing Communication Settings (V130/V350/V130J/V350J Only)

- To access the communication jumpers, hold the I/O PCB board by its top and bottom connectors and steadily pull the board off.
- 2. Locate the jumpers, and then change the settings as required, according to the jumpers' settings shown on page 12.

## **Closing the Controller**

- Gently replace the board. Make certain that the pins fit correctly into their matching receptacle.
   Do not force the board into place; doing so may damage the controller.
- 2. Replace the back cover of the controller and fasten the corner screws.

Note that you must replace the back cover securely before powering up the controller.

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